Sam Huggins

Unified Robotics II

Agile User Story

As a user, I want a fully autonomous, robotic pick and place system that provides quick and accurate results so that the shapes will be sorted correctly. It should have a setup phase, where the camera is positioned and the shapes are placed on the paper, and then a quick startup sequence to begin the pick and place. I know I am done once all of the pieces are sorted, the robot is safely powered off.